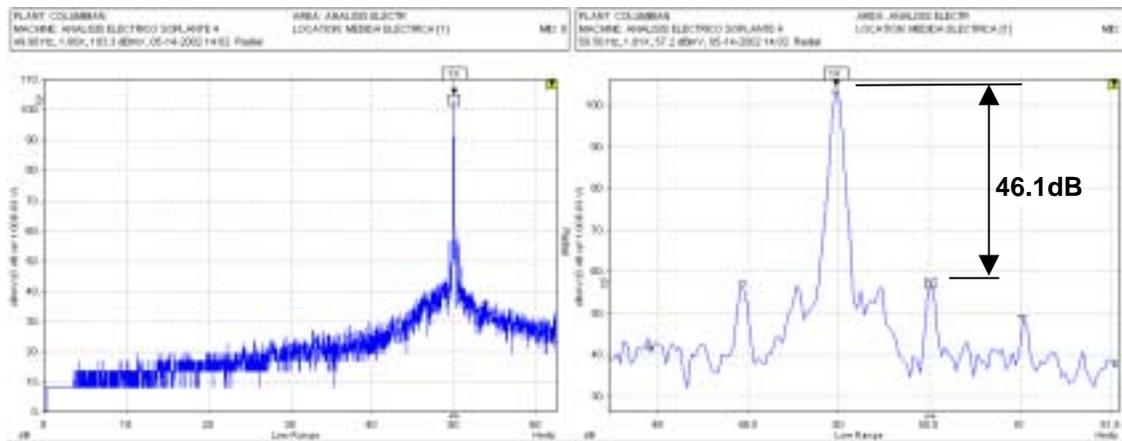


Motor Current Signature Analysis

by Mike Johnson

Modulation of the electrical line current occurs in an AC induction motor with a defective rotor bar. In a spectrum of motor current, this modulation creates pole pass sidebands around the line frequency peak (60 Hz in North America). The sideband spacing is equivalent to the slip frequency multiplied by the number of poles. As an example: In the USA a two pole motor operating at 3570 rpm has a pole pass frequency of 60 rpm (1 Hz). Therefore, we might expect to see a large peak at 60 Hz and sidebands at 59 and 61 Hz if the motor had a defective rotor bar. Outside of North America, the electrical line frequency is 50 Hz. An example of a motor in Europe follows.

Motor current signature was performed in Europe on a very large two pole induction motor operating at 2985 rpm. See the spectral data below. The 50 Hz line frequency peak is clearly seen in the spectrum on the left. In the zoomed spectrum on the right note the pole pass sidebands (30 rpm spacing) around the line frequency peak.



It is generally accepted that if the sidebands are more than 55 to 60 dB down from the 50 Hz peak, the rotor bars are considered good. If the sidebands rise to within 45 to 50 dB of the 50 Hz peak, damaged rotor bars are likely. When the delta is less than 40 dB, a cracked rotor bar is highly likely. It is important to state that these rules only apply for data taken from a motor that is loaded to at least 75% of its rated load. Additionally these rules apply regardless of whether line frequency is 50 or 60 Hz.

To set up the current clamp in EAV use the Setup selections below. Create a location with an F_{max} of about 10 to 15 Hz above the line frequency. With the motor under its normal full load, collect the data by placing one phase of the motor controller output inside the current clamp. Depending on the motor operating conditions you may need to vary the resolution setting and number of averages in the setup shown below.

Motor Current Signature Setup

(applicable for DC-X, DC-7 and DCA 31 using the DLI model 8525 current transformer)

General Tab	
<i>Cut-off frequency</i>	0 Hz
<i>Resolution</i>	1600 or 3200
<i>Transducer type</i>	Volts Dynamic
<i>ICP Current Source</i>	Not Checked
<i>Sensitivity</i>	10 mV/V
<i>Vibration units</i>	dBmV

Measurement Tab	
<i>Average type</i>	Spectral
<i>Number of averages</i>	6 to 20
<i>Average overlap %</i>	50%
<i>Window type</i>	Hanning
<i>Tachometer reference</i>	External tachometer
<i>Interrupt drive collection</i>	Off (normal)